

Company Name: _____

Company Number: _____

2019 MATE ROV COMPETITION

Innovations for Inshore: ROV Operations in Rivers, Lakes, and Dams

EXPLORER CLASS Non-ROV Device Power Specifications and Independent Sensors SAFETY CHECK LIST.

Companies must bring this check list with them to their safety inspection.

In 2019, only the micro-ROV qualifies as a non-ROV device.

<p>ELEC-NRD-001: Non-ROV devices can be powered from the surface or from batteries onboard the device. Power is limited to 12 VDC maximum and 6 amps maximum.</p>	<ul style="list-style-type: none"> Battery containers utilize a pressure release valve AND a Schrader valve. The pressure release valve must be rated no more than 3 psi.
<p>ELEC-NRD-002: The micro-ROV may contain cameras, thrusters and motors.</p>	<p>ELEC-NRD-004 Companies using a pressure release valve for their onboard battery container provided specifications and factory cut sheets of the valve used to the Competition Technical Manager no later than April 1st, 2019.</p>
<p>ELEC-NRD-003: If powered from the surface, the device must have a 7.5 amp fuse within 30 cm of the point of connection to the power source.</p>	<p>Pressure release approved <input type="checkbox"/></p>
<p>ELEC-NRD-004: Onboard power is allowed for non-ROV devices. If onboard batteries are being used, the following specifications must be met:</p>	<p>ELEC-NRD-005: An SID must be submitted for a Non-ROV device that uses electrical power.</p>
<ul style="list-style-type: none"> Batteries must be primary (non-rechargeable). 	<p style="text-align: center;">Independent Sensors</p>
<ul style="list-style-type: none"> AAA, AA, A, A23, C, D or 9V alkaline batteries are allowed. Alkaline batteries only. 	<p>ELEC-IS-001: Independent sensors must be powered from the surface; no onboard batteries are allowed.</p>
<ul style="list-style-type: none"> Batteries are mounted in a manner that they are not loose inside the container. 	<p>connect their sensor to a computer. Companies may also use surface battery packs (limited to 12 volts maximum) or the MATE supply to provide power for their independent sensor.</p>
<ul style="list-style-type: none"> A fuse (7.5 amps max) must be installed within 5 cm of the battery positive terminal. 	<p>ELEC-IS-003: The independent sensor may only contain the intended sensor; thrusters, cameras, or other systems MAY NOT be attached.</p>
<ul style="list-style-type: none"> The enclosure housing must be designed so that it will open if the pressure inside the housing is greater than the outside pressure 	<p>ELEC-IS-004: Companies that use an independent sensor must provide a 3 amp (or less) fast blow fuse on the positive side of their connection.</p>
<ul style="list-style-type: none"> Any pressure relief plug MUST be at least 2.5 cm in diameter. 	<p>ELEC-IS-005: An SID must be submitted for an independent sensor that uses electrical power.</p>
<ul style="list-style-type: none"> The enclosure housing must be designed so that it will release pressure if pressure inside the housing is greater than the outside pressure. Under no condition should the housing be built with fasteners to hold the device together if there is no pressure release valve. 	
<ul style="list-style-type: none"> The battery holder must be mounted in a manner that will allow the end cap to freely open if pressure develops inside the housing. 	