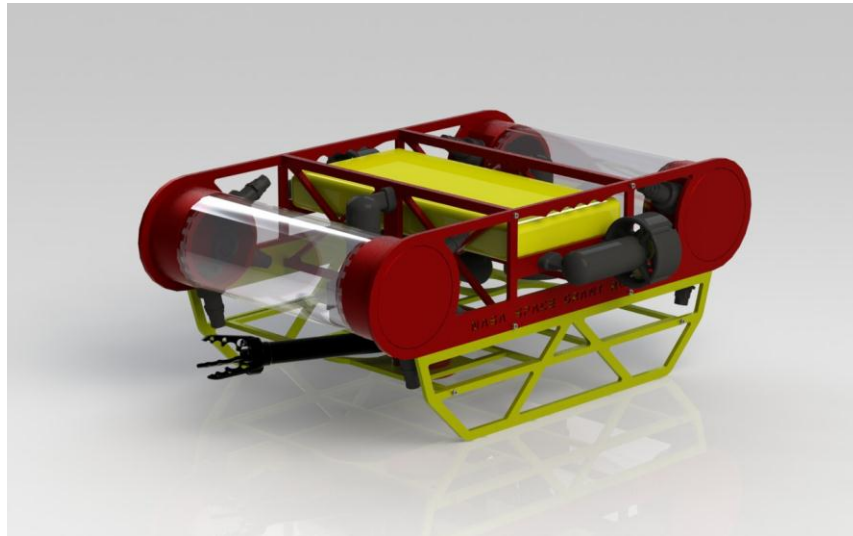


# NASA Space Grant Robotics

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Arizona State University, Tempe, Arizona



- **Koi**

- Stream line design for hydrodynamics
- 5 degrees of freedom movement including strafe and tilt
- Stereovision for surveying SS Gardner
- Seabotix Claw for manipulation
- Bilge Vacuum activated fuel retrieval device
- Camera systems on a controlled tilt axis
- Clearly displayed electrical enclosures