

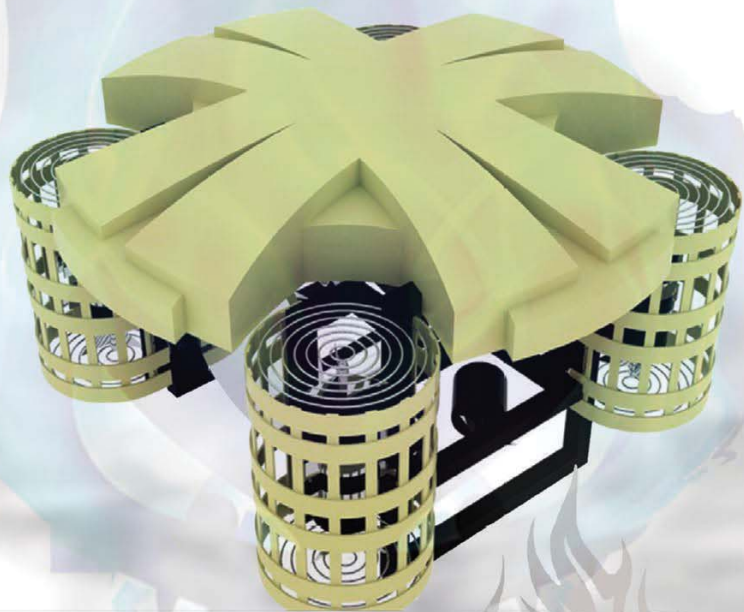
Nanjing Institute of Technology Spec Sheet

Our team is called **Challenger**. We are from Nanjing Institute of Technology, a popular university in Nanjing, Jiangsu province, China. It is a fairly long way from Nanjing to HONGKONG, it is the third time our team is participating in the MATE competition.

Our ROV has a pretty imposing name --- **Sea Wolf**, whose total expenses is about 29,256.50 yuan. In the perspective of design rationale, the revolutionary change of the ROV comes to the shift of the robot's major structure from the plate to the 440mm*440mm*80mm framework. The video system consists of three cameras. Symmetric distribution, which is convenient enough to make **Sea Wolf** move upward or downward. The direction driving motors at the bottom employ a similar Symmetric layout strategy at 45 degrees to the edges of **Sea Wolf** in order to control the translation and rotation of the ROV. Using the mode of ARM9+ cortex-m3 dual core processing architecture as the core control system, the control program is designed based on C and C++ programming language. Refers to the data transmission system, the network cables and serial ports are used at the same time for accurate transmission. When it comes to safety measures, aiming at protect the main chip, a fuse was installed in the main circuit to prevent the large short-circuit current burning out the chip. Furthermore, handmade protective screenings around the motors can greatly reduce the potential harm caused by the contact between our hands and the propellers. Besides, we use a multimeter to confirm whether every circuit connection is correct carefully.

TEAM MEMBER:

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Pengyu Zhang	Soft Engineer
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德想
SEA WOLF

TEACHER GUILD:

Hanqi Yu	Doctor
Wei Chen	Associate Professor
Xianglin Ma	Associate Professor
Ximing Xia	Doctor
Jun Zhang	Lecture
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